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# All-weather tropospheric **3D Wind** from microwave sounders

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## AMV: GOES and similar geostationary satellites

- Method: Track cloud and water vapor features
- Observations used: Brightness temperatures  $\Rightarrow \sim T(\text{feature})$
- Height registration: Forecast  $T(z) \Rightarrow \sim z(\text{feature})$
- Pros: Very frequent obs. (5-15 min); covers large portion of a hemisphere
- Cons: Uncertain height registration; limited coverage

## AMV: MODIS

- Method: Similar to GOES
- Coverage: Polar regions only
- Pros: Polar-region coverage complements GOES
- Cons: Uncertain height registration; infrequent obs. ( $\leq 100$  min); limited coverage

## CMV: MISR

- Uses parallax motion from multi-angle cameras during 7-minute overflight interval
- Pros: Precise height registration
- Cons: Cloud top winds only; limited dynamic range; sparse global coverage

**All cloud methods: Poor coverage in mid-troposphere due to few clouds there**

## Doppler lidar: Coming (soon?)

- Pros: Very high vertical resolution; precise height registration
- Cons: Obscured by clouds; sparse coverage; limited laser life time



## AMV: Track water vapor features

- Method: Track water vapor features (similar to GOES and MODIS)
- Observations used: Retrieved  $q(z,t)$  – no need for forecast input
- Height registration: Absolute (referenced to  $p_{\text{surface}}$ )
- Pros: Accurate height registration; uniform coverage throughout troposphere
- Cons: Moderate spatial resolution ( $\sim 2$  km vertically, 5-25 km horizontally)

## Infrared sounders (current)

- Example: AIRS (Aqua), CrIS (S-NPP)
- Coverage: Polar regions only (similar to MODIS)
- Cons: Infrequent obs. ( $\leq 100$  min); limited coverage; obscured by clouds

## Microwave sounders (current)

- Example: AMSU (NOAA), ATMS (S-NPP) – Coming soon: CubeSat MW sounders
- Coverage: Polar regions only (similar to MODIS)
- Pros: Penetrates clouds
- Cons: Coarse spatial resolution

## Challenge: Temporal sampling

- All are polar-orbiting LEO satellites  $\Rightarrow$  polar coverage only, long sampling intervals
- Requirement: Sampling interval  $\sim 5$ -20 minutes
- Solution: Small-sat (LEO) cluster; Large-sat (GEO) single sensor  $\leftarrow$  Best solution!

## **GEO sensors achieve high temporal resolution: minutes**

- Important for observations of highly dynamic processes and phenomena
- Ideal for wind measurements through feature tracking
- Ideal for monitoring of high-intensity short-duration precipitation events

## **GEO sensors provide continuous coverage: minutes → days → weeks**

- Important for observation of storm life cycles
- Important for rain totals (storms or regions)

## **IR sounders: Clouds are problematic**

- Need to do “hole hunting” or limit to above-clouds
- Can’t get observations in or below clouds

## **Best: MW sounders**

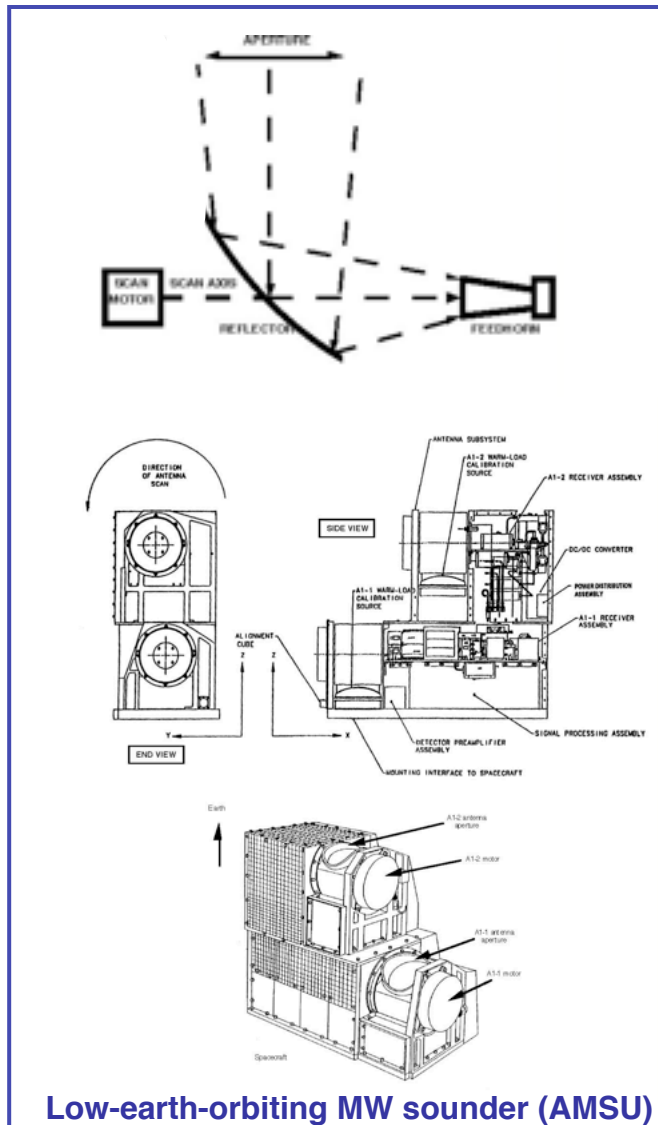
- Meteorologically “interesting” scenes: Full cloud cover; Severe storms & hurricanes
- Cloud liquid water distribution
- Precipitation & convection
- Above all: Can observe water vapor features through clouds → Wind everywhere





# So why don't we already have GEO/MW?

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Low-earth-orbiting MW sounder (AMSU)

## The antenna is the key, and the problem...

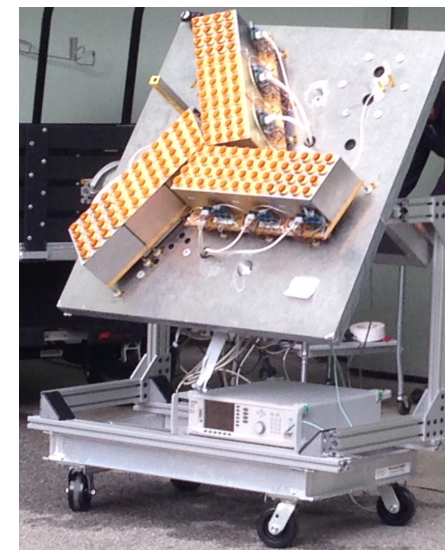
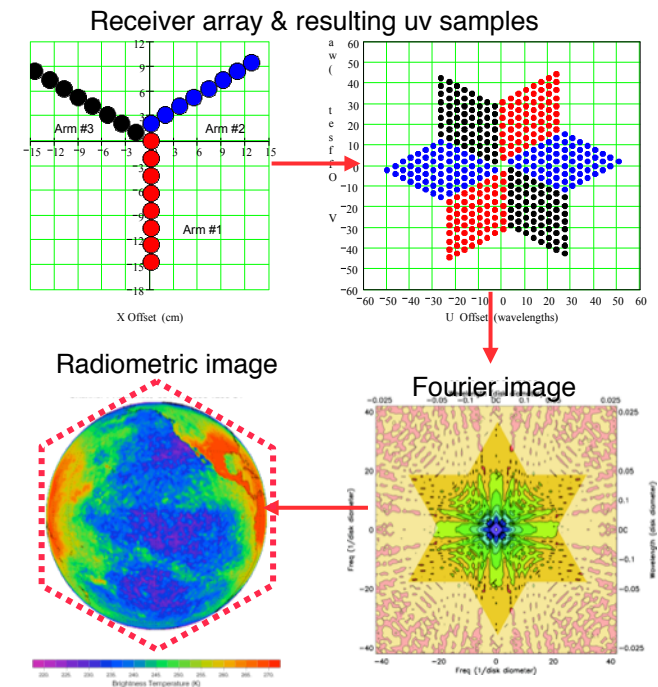


- Antenna size is determined by distance and “spatial resolution”
- AMSU antenna is 15 cm dia.  $\Rightarrow$  50-km resolution from 850 km
- GEO orbit is  $\sim 36000$  km  $\approx 42 \times 850$  km
- AMSU-antenna must then be  $42 \times 15$  cm to give 50-km res. from GEO
- This is 6.5 meters! Not feasible!  
This can be reduced somewhat by degrading the antenna efficiency - but still impractical
- Solution: *Synthesize* large antenna  $\Rightarrow$  GeoSTAR

- **Aperture-synthesis concept**
  - Sparse array employed to synthesize large aperture
  - Cross-correlations -> Fourier transform of Tb field
  - Inverse Fourier transform on ground -> Tb field
- **Array**
  - Optimal Y-configuration: 3 sticks; N elements
  - Each element is one I/Q receiver,  $3.5\lambda$  wide (2.1 cm @ 50 GHz; 6 mm @ 183 GHz!)
  - Example:  $N = 100 \Rightarrow \text{Pixel} = 0.09^\circ \Rightarrow 50 \text{ km at nadir (nominal)}$
  - One “Y” per band, interleaved
- **Other subsystems**
  - A/D converter; Radiometric power measurements
  - Cross-correlator - massively parallel multipliers
  - On-board phase calibration
  - Controller: accumulator -> low D/L bandwidth

This is the only viable “array spectrometer” design and is what the NRC had in mind

Proof-of-concept prototype developed at JPL





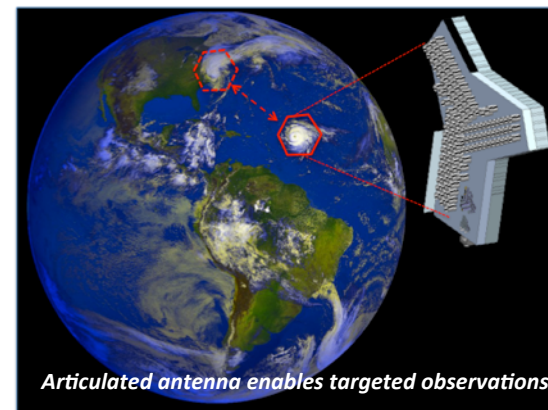
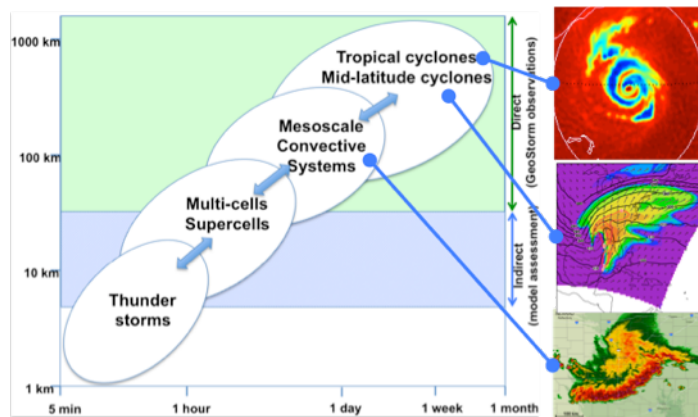
# "GeoStorm": A GEO/MW mission concept

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## A GEOSTATIONARY MICROWAVE SOUNDER MISSION FOCUSED ON THE EVOLUTION OF SEVERE STORMS

*Improve our understanding of sudden and unpredicted change in intensification and motion of destructive storms:*

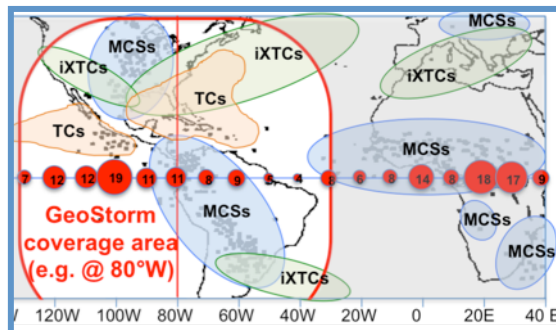
- *hurricanes*
- *severe thunderstorms and mesoscale convective systems*
- *mid-latitude cyclones and winter storms*



*Articulated antenna enables targeted observations*

Low cost as a hosted payload

Many hosting opportunities in GEO:



There are more than 80 GEO comm-sats that provides a view of the Americas, being replaced at a rate of 5-6 per year

### GeoStorm Highlights

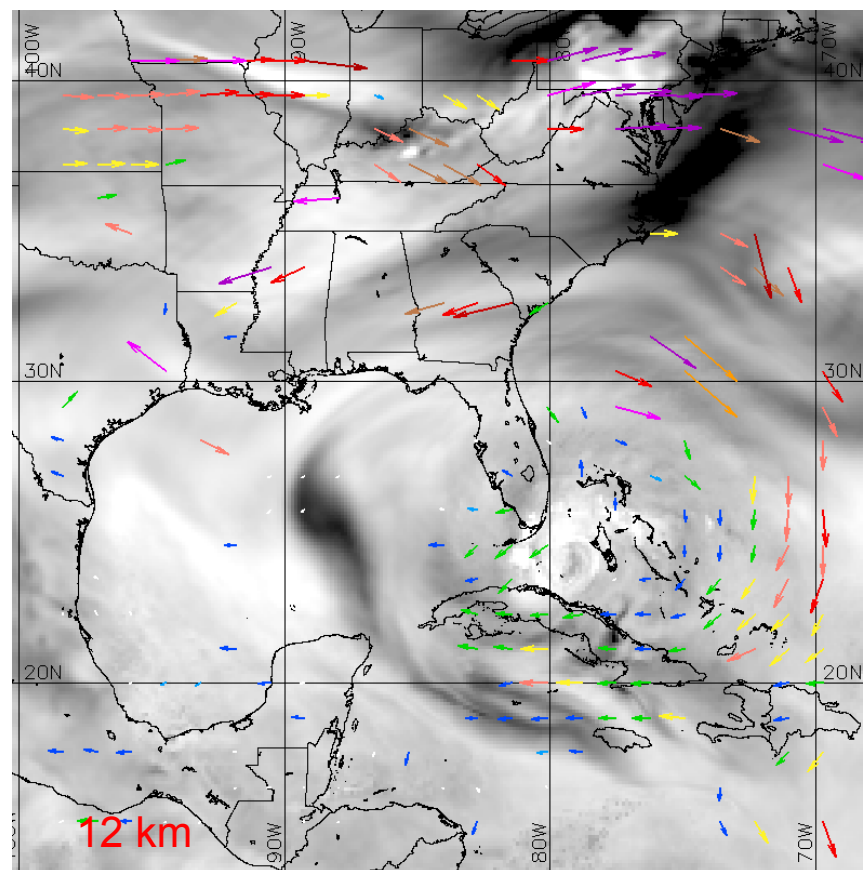
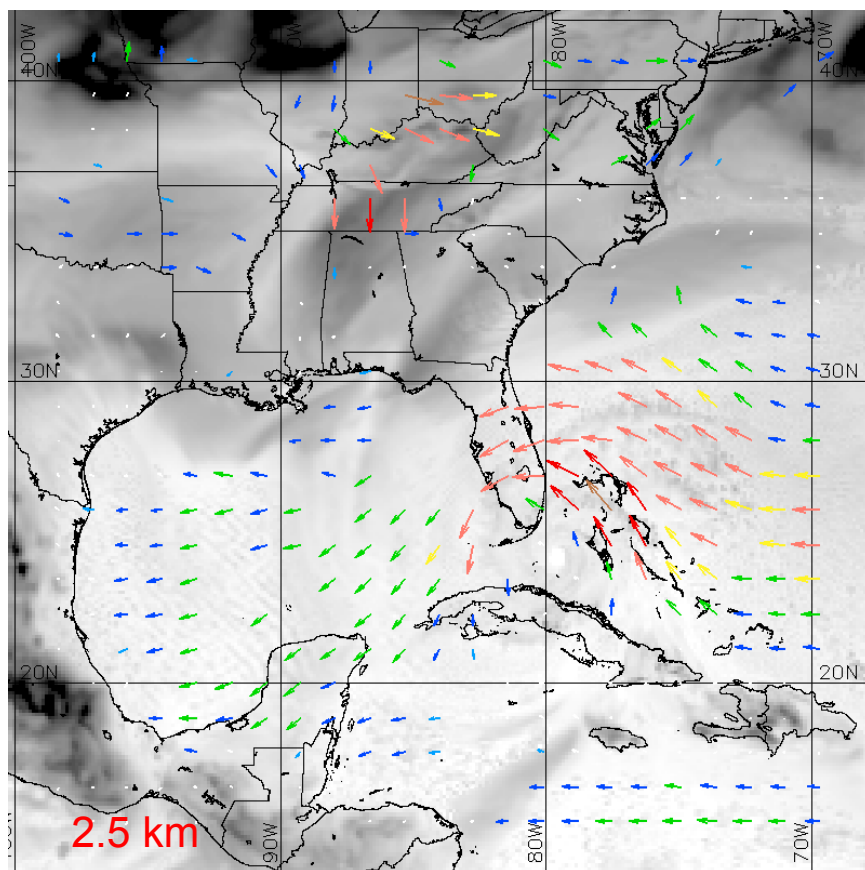
Targeted observations	Life cycle storm tracking
Time-continuous	Capture dynamic processes; diurnal cycle fully resolved
Multiple simultaneous key parameters	Temperature, humidity, precipitation, wind
All-weather	Cloud/rain-penetrating
3-D observations	1000 km dia x 15 km vert. (volume); 25 km dia x 3 km vert. (resolution)
Wide coverage	All storms visible from GEO

This mission concept was used as the basis for an OSSE study of 3D wind capabilities





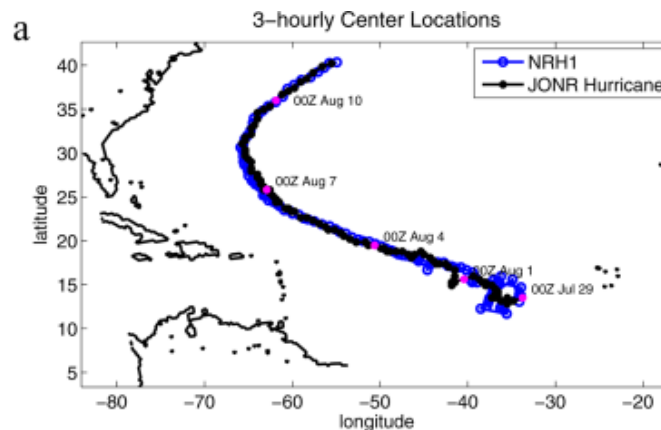
## WRF simulation of Rita (2005)



Credit: S. Hristova-Veleva & J. Turk, JPL

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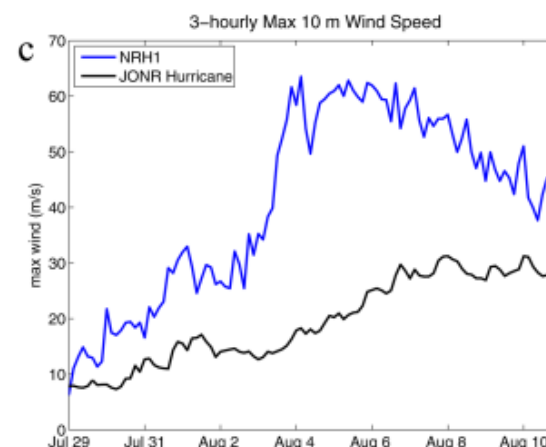
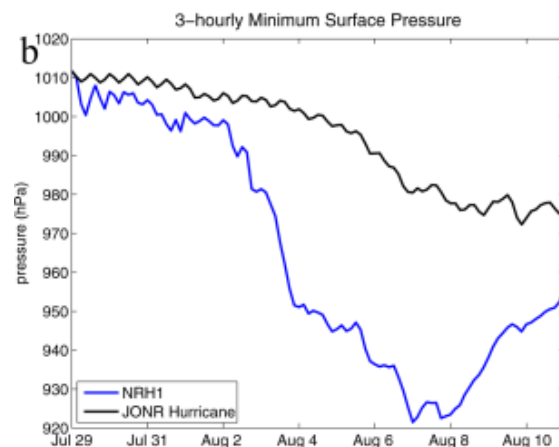
## WRF simulation embedded in global model; developed by NOAA Simulates NATL hurricane for 13 days



**Four nested grids:**

1. 27 km 30 minutes (240x160)
2. 9 km 30 minutes (120x120)
3. 3 km 30 minutes (240x240)
4. 1 km 6 minutes (480x480)

**The 3 innermost grids follow the storm**



**Journal of Advances in Modeling Earth Systems**

[Volume 5, Issue 2](#), pages 382-405, 13 JUN 2013 DOI: 10.1002/jame.20031

<http://onlinelibrary.wiley.com/doi/10.1002/jame.20031/full#jame20031-fig-0004>

## Simulated $q(x,y,z,t)$ derived from nature run fields

- Replicate GeoStorm spatial resolution
- Replicate GeoStorm temporal sampling
- Replicate GeoStorm precision
- Used primarily Grid 4 (1 km, 6 minutes)

## Horizontal spatial

- Convolve NR with **25-km** gaussian  $\Leftrightarrow$  25-km horizontal resolution

## Vertical resolution

- Convolve NR with AMSU-like averaging kernels  $\Leftrightarrow$  **2-3 km** vertical resolution

## Temporal

- Convolve NR with 15-minute box-car averaging kernel  $\Leftrightarrow$  **15-minute** averaging

## Noise

- Add **~25% random noise** to convolved  $q$

## Precipitation filtering according to MIRS retrieval capabilities

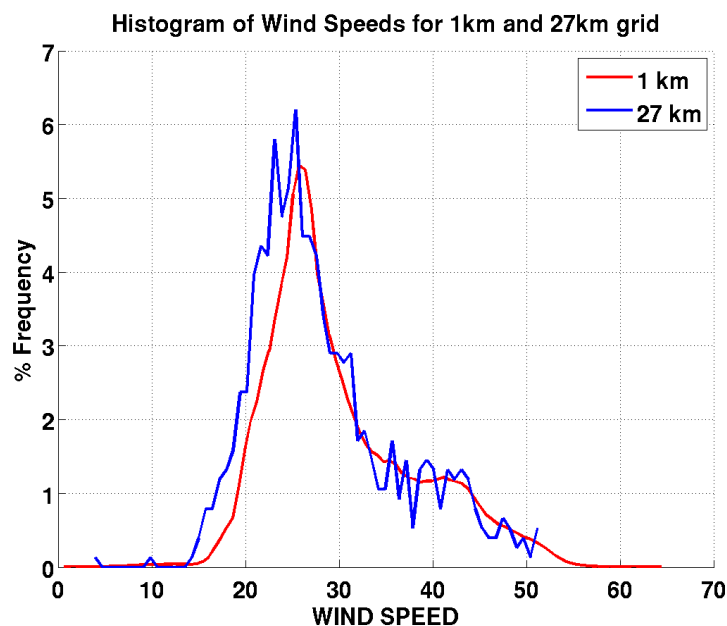
- Rain rate  $< 1$  mm/hr: All cases accepted
- Rain rate  $> 1$  mm/hr and  $< 3$  mm/hr: Only above 700 mb accepted
- Rain rate  $> 3$  mm/hr: All cases rejected





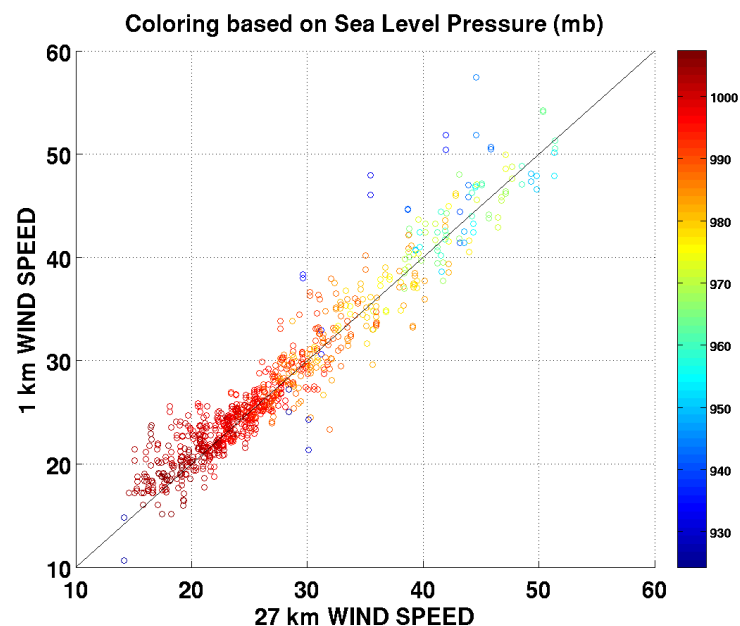
# Some NR wind statistics

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NR wind speed distribution for Grid 1 (blue) and Grid 4 (red)

Shows that model wind does not strongly depend on spatial scale



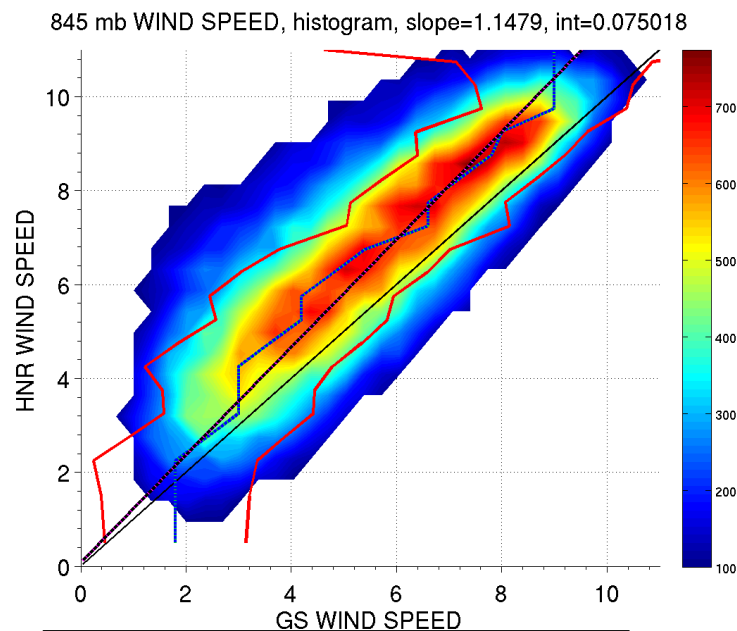
NR wind speed vertical distribution for Grid 1 (horizontal axis) and Grid 4 (vertical axis)

Shows that vertical distribution of wind also does not strongly depend on spatial scale

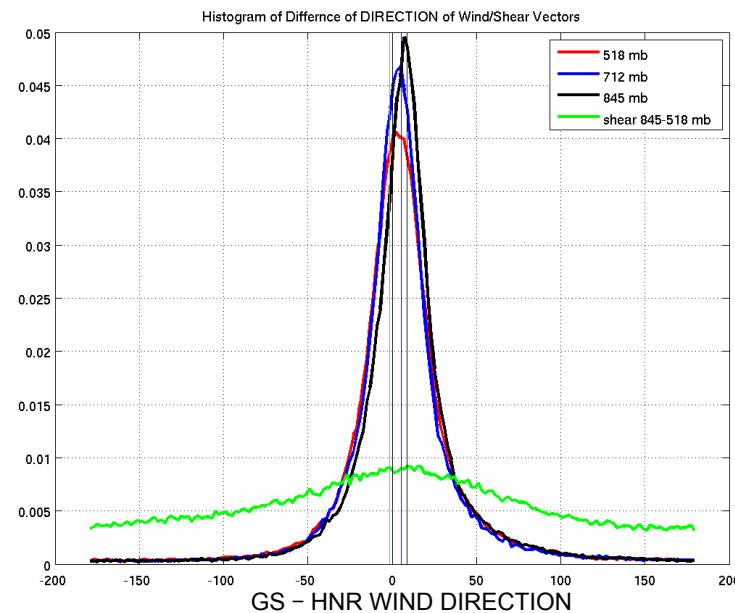
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Based on large sample size (> 5000); cases with rain rate < 1 mm/hr

## Wind speed: Histogram @ 845 mb



## Wind direction: 3 pressure levels



## Summary:

**Precision < ± 2 m/s - This meets WMO requirements for wind**

Pressure level (mb)	Bias	RMS error
518	-0.8 m/s    2°	1.9 m/s    14°
712	-1.2 m/s    3°	1.6 m/s    11°
845	-1.0 m/s    6°	1.7 m/s    10°

## How to achieve adequate temporal sampling from LEO

- Frequent overpasses: Polar regions (polar-orbiting satellites)
- Multiple satellites: E.g., 2xMODIS, nxAMSU
- Cluster of small-sats

## Nominal architecture

- 3 CubeSats flying in formation, 5-15 minutes apart
- Each has a MW sounder (e.g., MASC)
  - Minimum capability: water vapor sounding, T also desirable

## Nature run

- WRF simulations of pre-hurricane tropical atmosphere, 1 hour
- 4-km grid
- 5-minute intervals  $\Leftrightarrow$  11 samples in 1 hour

## Simulations

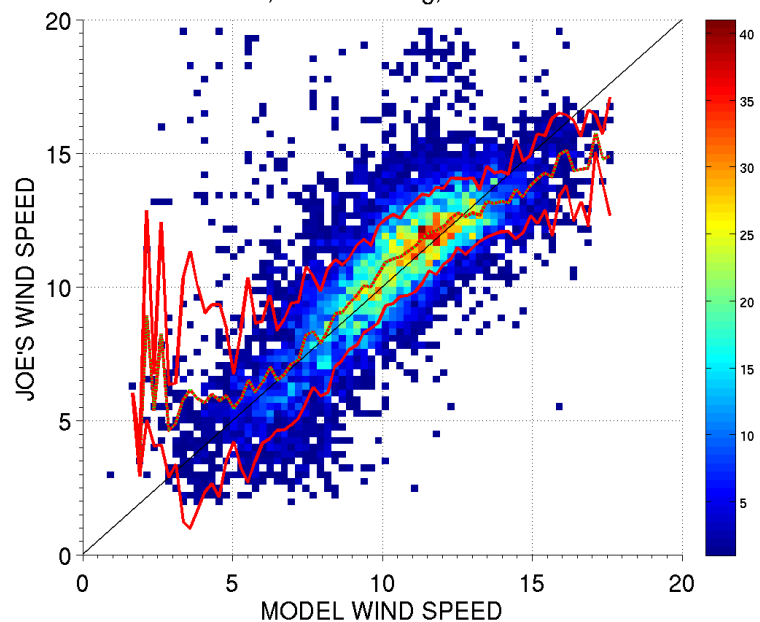
- Convolve with AMSU averaging kernels  $\Leftrightarrow$  2-3 km vertical resolution
- NR temporal & horizontal sampling  $\Leftrightarrow$  4 km horizontal resolution. 5-minutes
- Precipitation filtering:  $< 1$  mm/hr only
- Noise: Same as for GEO case



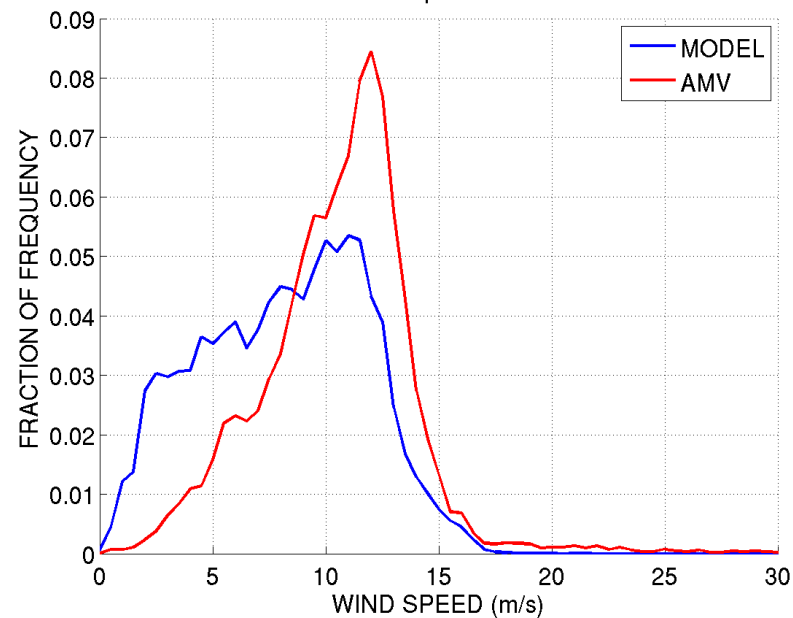
# LEO constellation simulation results

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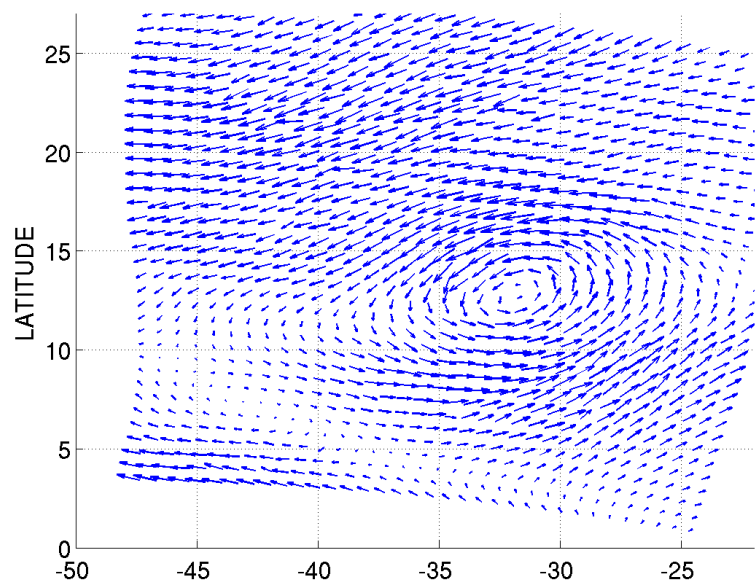
2-D HISTOGRAM, vert smoothing, 848 mb WIND SPEED



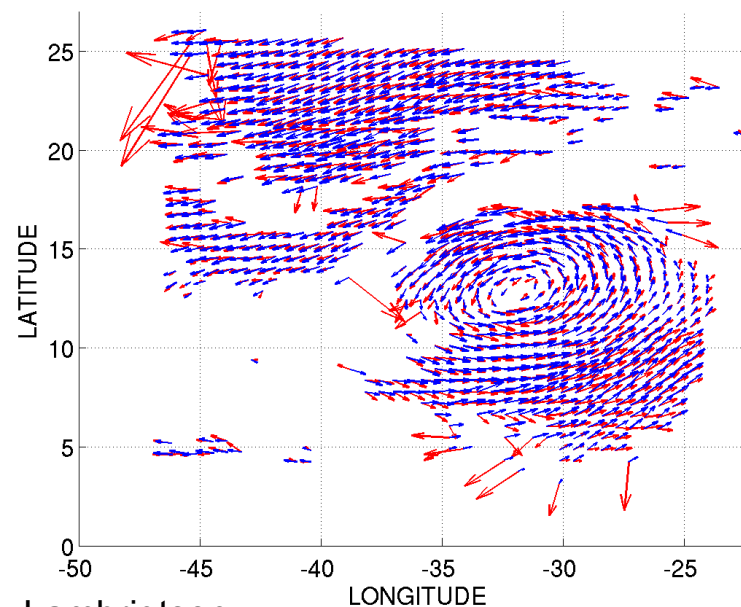
PDF of wind speeds at 848 mb



Model wind vectors at 848 mb



Wind vectors at 848 mb, red=JOE'S AMV, blue=MODEL



January 10, 2018

AMS 2018 --- Lambriatsen



- Both simulations yield  $< \pm 2$  m/s precision, low bias
  - GEO simulations have robust statistics
  - LEO simulations based on small sample
  - Accuracy & precision are not sensitive to instrument noise
    - Due to spatial averaging by AMV algorithm (32x32 box pattern detector)
    - To be investigated further
- Rain is only a minor factor
  - MW sounders are not affected by clouds
  - Even tropical cyclones exceed 3 mm/hr in relatively small areas
  - Advanced retrieval systems can account for rain
    - System developed at JPL (Schreier, *personal comm*) works at  $\sim 10$  mm/hr
- Future work
  - Determine dynamic range & precision vs.  $\Delta t$  and  $\Delta x, \Delta y$
  - See if AMV algorithms can be improved
  - Apply resolution enhancement to GEO case  $\rightarrow$  5-10 km, 5 min
    - Algorithms developed at JPL (Yanovsky, *JSTAR, Rem.Sens.Lett.*)